

<<library>>



Rover

- roverID = 0 : int;
- followerID = 0 : int;
- isLeader = false : bool;
- isFollower = true : bool;
- leave = false : bool;
- hasFollower = false : bool;
- hasPredecessor = true : bool;
- targetOrdinate = 120 : int;
- nbCycles = 0 : int;

- ~ in inputMessage(int t, int c)
- ~ out outputMessage(int t, int c)
- ~ in sensedData(int g, bool l, bool p)
- ~ out sense(int t, bool f, bool p)
- ~ out toEnvironment(int v, int h)